

## Sec. 3.1 Review of Calc. II :

9-1

### Equations of lines & planes in $\mathbb{R}^2$ and $\mathbb{R}^3$ .

In this Chapter we'll study so-called "vector spaces and subspaces" in  $\mathbb{R}^n$  and their properties. We'll introduce a definition of a vector space later. For now, it will suffice to know that  $\mathbb{R}^n$  is the set of all vectors with  $n$  real components.

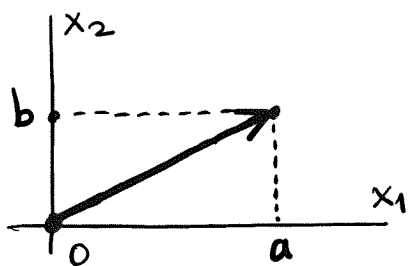
Notation:

$$\mathbb{R}^2 = \left\{ \underbrace{\underline{x}}_{\text{"all } \underline{x}} : \underbrace{\text{such that}} \underbrace{\underline{x} = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}, x_1, x_2 = \text{real}}_{\text{condition satisfied by } \underline{x}} \right\}$$

Why we care about the special cases of  $\mathbb{R}^2$  &  $\mathbb{R}^3$ ?

Most properties of  $\mathbb{R}^n$  can be understood using the properties of lines in  $\mathbb{R}^2$  and lines & planes in  $\mathbb{R}^3$ . We cannot visualize vectors in  $\mathbb{R}^n$  for  $n > 3$ , but we can visualize vectors, lines and planes in  $\mathbb{R}^2$  and  $\mathbb{R}^3$ .

① Eq. of a line in  $\mathbb{R}^2$  which goes through  $(0,0)$  along vector  $\langle a, b \rangle$ .



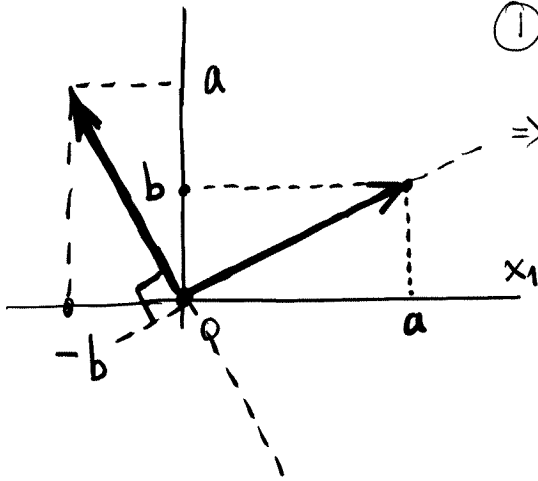
$$\begin{cases} x_1 = at \\ x_2 = bt \end{cases}$$

(Usual notations:  
 $x = at$   
 $y = b \cdot t$ )

Check:  $y = b \cdot t = b \cdot \frac{x}{a} = \left(\frac{b}{a}\right) \cdot x$  ✓  
↖ slope

Notation:  $\left\{ \underline{x} : \underline{x} = \begin{pmatrix} at \\ bt \end{pmatrix}, t = \text{any real} \right\}$

② Alternative form of ①



①  $\Rightarrow x_1 = at, x_2 = bt$

$\Rightarrow -b \cdot (at) + a \cdot (bt) = 0$

$-bx_1 + ax_2 = 0$

call this A      call this B

$A \cdot x_1 + B \cdot x_2 = 0$

Memorize: An object is a line in  $\mathbb{R}^2$  going through  $(0,0)$  if and only if its equation has either of the forms given in ① and ②.

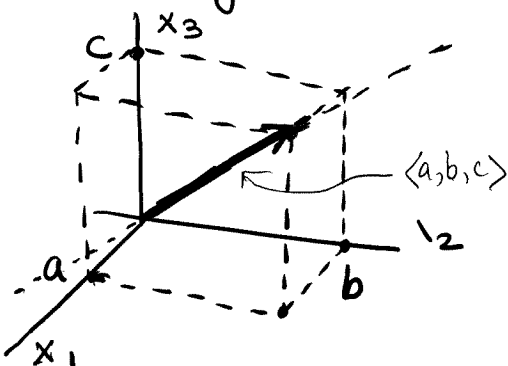
Note:  $Ax_1 + Bx_2 = 0 \Leftrightarrow \begin{pmatrix} A \\ B \end{pmatrix}^T \cdot \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = 0$

$\Leftrightarrow \begin{pmatrix} A \\ B \end{pmatrix} \perp \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \leftarrow \text{this is what we see in the sketch above}$   
 $\begin{pmatrix} -b \\ a \end{pmatrix} \parallel \begin{pmatrix} a \\ b \end{pmatrix}$

③ Eq. of a line in  $\mathbb{R}^2$  (not) through origin

$Ax_1 + Bx_2 = C, C \neq 0.$

④ Eq. of a line in  $\mathbb{R}^3$  going through origin along vector  $\langle a, b, c \rangle$ .



$\left\{ \underline{x} : \underline{x} = \begin{pmatrix} at \\ bt \\ ct \end{pmatrix}, t = \text{any real} \right\}$

Note: Eq. of a line in  $\mathbb{R}^3$  **cannot** be written as  $Ax_1 + Bx_2 + Cx_3 = 0$

In fact, to define a line in  $\mathbb{R}^3$ , we need two eqs., not one! See Ex. 2 below.

⑤ Eq. of a plane in  $\mathbb{R}^3$  that is perpendicular to vector  $\langle a, b, c \rangle$ :

$$Ax_1 + Bx_2 + Cx_3 = D \quad (\star)$$

If  $D=0 \Rightarrow$  the plane goes through the origin.

Ex. 1 What is  $\{ \underline{x} : \underline{x} = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}, x_2 = x_1 \}$ ?

Sol'n: We see that this is in  $\mathbb{R}^3$ , so it can be either line (④) or plane (⑤). It does not appear like the eq. in (④). So it must be (⑤). Indeed, put eq.  $x_2 = x_1$  in the form ( $\star$ ):

$$\begin{array}{ccccccc} 1 \cdot x_1 + (-1) \cdot x_2 + 0 \cdot x_3 & = & 0 \\ \uparrow & & \uparrow & & \uparrow & & \uparrow \\ A & & B & & C & & D \end{array}$$

So, this is a plane  $\perp$  vector  $\begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix}$ , and since  $D=0$ ,  $\Rightarrow$  this plane goes through the origin.

Geometric interpretation: count "degrees of freedom"

$$\begin{array}{ccc} 3 & - & 1 & = & 2 \\ \text{(in } \mathbb{R}^3 \text{ one has)} & & \text{(1 constaining)} & & \text{(}\# \text{ of remaining)} \\ 3 \text{ DoF} & & \text{equation} & & \text{DoF} \end{array}$$

A plane has 2 DoF, but a line has only 1 DoF.

Ex. 2 What is  $\{ \underline{x} : \underline{x} = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}, x_1 = x_2 \text{ and } x_2 = -x_3 \}$ ?

Sol'n: Write each constraining eq. in form  $(\star)$ :

$$\text{Eq. 1} \Rightarrow 1 \cdot x_1 + (-1) x_2 + 0 \cdot x_3 = 0 \quad \leftarrow \text{a plane through } (0,0,0)$$

$$\text{Eq. 2} \Rightarrow 0 \cdot x_1 + 1 \cdot x_2 + 1 \cdot x_3 = 0 \quad \leftarrow \text{another, non-parallel plane through } (0,0,0)$$

The "and" says that  $\underline{x}$  belongs to both planes.

Therefore, it is the intersection line of these planes, and goes through origin because each plane goes through origin.

Thus, answer: this is a line in  $\mathbb{R}^3$ .

Note: A line in  $\mathbb{R}^3$  is defined by two, not one, eq.

Geometric interpretation: count "degrees of freedom"

$$\begin{array}{rcccl} 3 & - & 2 & = & 1 \\ \text{(3 DoF in } \mathbb{R}^3) & & \text{(2 constraining} & & \text{(# of remaining} \\ & & \text{eqs.)} & & \text{DoF)} \end{array}$$

1 DoF  $\Rightarrow$  a line. //