

Sec. 16.7: Surface integrals

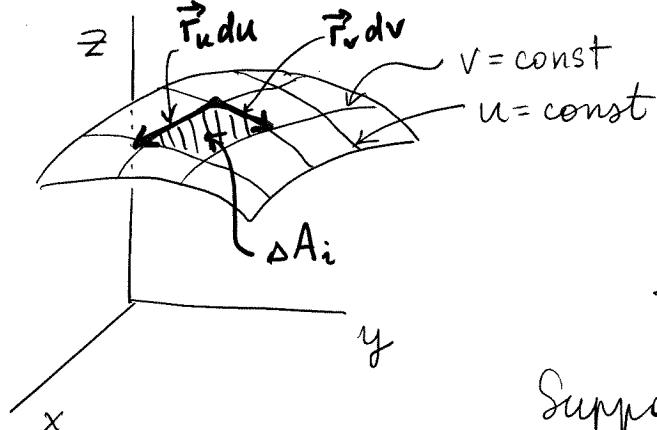
For line integrals (sec. 16.2), we had 2 types:

1: $\int_C f(x, y, z) ds$, meaning = mass of a wire C
(and similar)

2: $\int_C \vec{F} \cdot d\vec{r}$, meaning = work done by \vec{F} along C.

For surface integrals, we'll also have 2 types.

① Mass of a curved sheet



As in sec. 16.6,
consider the param.
surface $\vec{r} = \vec{r}(u, v)$,
or, equivalently,

$$\vec{r} = \langle x(u, v), y(u, v), z(u, v) \rangle.$$

Suppose this curved sheet has mass surface density $\delta(x, y, z)$. To find the mass of the sheet, we proceed as in sec. 16.6 (topic 2C), where we wanted to find the surface area. Namely, we "draw" a mesh of curves ($u = \text{const}$, $v = \text{const}$). This mesh subdivides the sheet into small tiles. Similarly to sec. 16.6 (for the area), we find the mass:

$$\begin{aligned} M_{\text{total}} &= \sum_i \Delta M_i \approx \sum_i \delta(x_i, y_i, z_i) \Delta A_i \quad \text{sec. 16.6} \\ &= \sum_i \delta(x(u_i, v_i), y(u_i, v_i), z(u_i, v_i)) \cdot |\vec{r}_u \times \vec{r}_v| du dv \quad \text{topic 2C} \end{aligned}$$

Thus, total mass of the curved sheet $\vec{r} = \vec{r}(u, v)$:

$$M = \iint_D \delta(x(u, v), y(u, v), z(u, v)) |\vec{r}_u \times \vec{r}_v| dudv \quad (*)$$

region in (u, v) -plane that corresponds to the particular patch of the surface (see below).

denoted by dS
in book;
elementary surface area

Note 1: When $\delta = 1$ for all (u, v) , the above formula reduces to the formula of the area of the sheet (sec. 16.6).

Note 2: If $(u, v) = (x, y)$ and $\Rightarrow z = f(x, y)$ (the familiar Cartesian surface), then

$$M = \iint_D \delta(x, y, z) \cdot \underbrace{\sqrt{f_x^2 + f_y^2 + 1}}_{\substack{\text{projection of the sheet} \\ \text{on the } (x, y)\text{-plane}}} dx dy$$

$\uparrow |\vec{r}_x \times \vec{r}_y|$, see the
Note on p. 27-5 (sec. 16.6)

Note 3(a): Note that in the formula (*) above we do not need to "add" the Jacobian $\left| \frac{\partial(x, y)}{\partial(u, v)} \right|$ "by hand", because we are not changing coordinates from (x, y) to (u, v) . Rather, we work with (u, v) from the start.

Note 3(b): The Jacobian, nonetheless, appears in the formula automatically: it is the factor $|\vec{r}_u \times \vec{r}_v|$; see p. 26-7 (sec. 15.9).

See Ex. 1, 2, 3 in book for numeric examples.

Ex. 1 Evaluate the surface integral

$$I = \iint_S (y^2 z^2) dS,$$

can think of this
as the surface
mass density

where S is the part of cone $z = 2\sqrt{x^2 + y^2}$ that lies between the planes $z=1$ & $z=3$.

Sol'n:

1) Sketch - to visualize what is being asked.

S = side surface of the cone shown on the right.

2) We found in Ex. 3 of Sec. 16.6 (p. 27-9) that

$|\vec{r}_u \times \vec{r}_v|$ and the integration

region \mathcal{D} look simpler in polar coords:

$$\vec{F} = \langle x, y, z \rangle = \langle r\cos\theta, r\sin\theta, 2r \rangle.$$

so we use $(u, v) = (r, \theta)$.

3) Find region \mathcal{D} (=integration limits) in (r, θ) -plane:

$$1 \leq z \leq 3 \leftarrow \text{given}$$

$$1 \leq 2r \leq 3 \leftarrow \text{since } z = 2r \text{ on the cone}$$

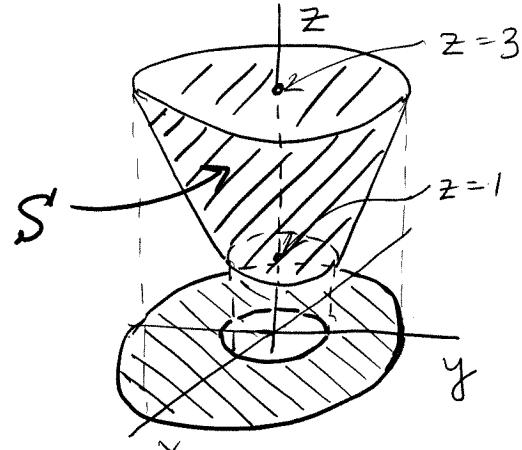
$1/2 \leq r \leq 3/2$

The book uses these notations:

S - the curved surface

dS - elementary area on the curved surface

(like previously, in Chap. 15, dA meant the elementary area in the xy -plane)



For θ , we have full rotation, so $0 \leq \theta \leq 2\pi$.

4) Compute $|\vec{r}_r \times \vec{r}_\theta|$. (similar to Ex. 3/sec. 16.6)

$$\vec{r} = \langle r\cos\theta, r\sin\theta, 2r \rangle$$

$$\vec{r}_r = \langle \cos\theta, \sin\theta, 2 \rangle; \quad \vec{r}_\theta = \langle -r\sin\theta, r\cos\theta, 0 \rangle$$

$$\vec{r}_r \times \vec{r}_\theta = \langle -2r\cos\theta, -2r\sin\theta, r \rangle; \quad |\vec{r}_r \times \vec{r}_\theta| = \boxed{\sqrt{5} \cdot r}$$

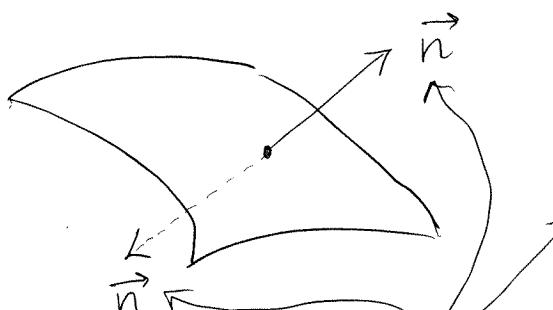
5) Substitute and evaluate:

$$\begin{aligned} \iint_S y^2 z^2 dS &= \iint_D \underbrace{(r\sin\theta)^2}_{y^2} \cdot \underbrace{(2r)^2}_{z^2} \cdot \underbrace{\sqrt{5} \cdot r}_{|\vec{r}_r \times \vec{r}_\theta|} \cdot dr d\theta \\ &= \int_0^{2\pi} \sin^2\theta \left(\int_{1/2}^{3/2} \sqrt{5} \cdot r^5 dr \right) d\theta, \quad \text{Note again: just } dr d\theta, \text{ not } r dr d\theta. \\ &\quad \text{half-angle formula} \\ &\quad (\text{Sec. 7.2, Ex. 3 or Sec. 15.3, Ex. 1/Notes}) \end{aligned}$$

$$\frac{4}{6} \pi \cdot \sqrt{5} \left(\left(\frac{3}{2}\right)^6 - \left(\frac{1}{2}\right)^6 \right)$$

Answer

② Orientation of a smooth surface



unit normal vector to surface $\vec{r} = \vec{r}(u, v)$

In sec. 16.6 (topic 2B), p. 27-4) we derived:

$$\vec{n} = \pm \frac{\vec{r}_u \times \vec{r}_v}{|\vec{r}_u \times \vec{r}_v|}$$

Chosen based on where \vec{n} is said to point.

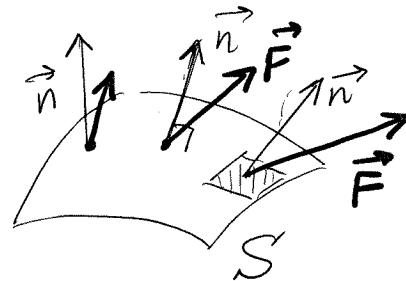
divide by length to make \vec{n} a unit vector

③ Flux of field \vec{F} through surface S

$$\iint_S (\vec{F} \cdot \vec{n}) dS$$

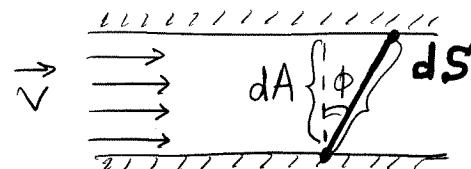
Flux = flow

This is the 2nd type of surface integrals, mentioned on p. 33-1.



Derivation of the above formula for flux:

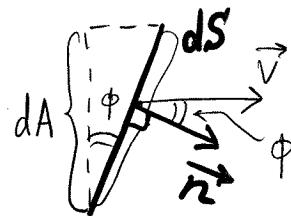
Consider the uniform flow of a fluid through an elementary area dS :



Flow through dS =

flow through dA ($\perp \vec{v}$) =

$$|\vec{v}| \cdot dA = |\vec{v}| \cdot (dS \cdot \cos \phi) =$$



$$\frac{\text{ft}}{\text{sec}} \cdot \frac{\text{ft}^2}{\text{sec}} = \frac{\text{ft}^3}{\text{sec}}$$

$$dA = dS \cdot \cos \phi$$

$$= |\vec{v}| \cdot |\vec{n}| \cos \phi \cdot dS = (\vec{v} \cdot \vec{n}) dS$$

Thus, for the flow through a finite sheet S :

$$\begin{aligned} \boxed{\text{Flux of } \vec{F} \text{ through } S} &= \iint_S (\vec{F} \cdot \vec{n}) dS = \iint_D \vec{F} \cdot \left(\pm \frac{\vec{r}_u \times \vec{r}_v}{|\vec{r}_u \times \vec{r}_v|} \right) \cdot \frac{|\vec{r}_u \times \vec{r}_v|}{dS} dudv \\ &= \iint_D \vec{F} \cdot (\pm \vec{r}_u \times \vec{r}_v) dudv \end{aligned}$$

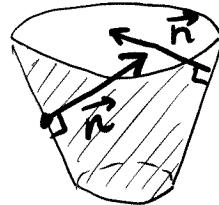
"projection" of S on (u,v) -plane

See Ex. 4, 5 in book.

Ex. 2 Let S be the surface of the cone in Ex. 1. Let \vec{n} be directed inside the cone. Find the flux of $\vec{F} = \langle -y, x, 3z^2 \rangle$ through this S .

Sol'n: 1) Write the general formula:

$$\text{Flux} = \iint_D \vec{F} \cdot (\pm \vec{r}_u \times \vec{r}_v) \, du \, dv$$



2) Specify $u, v, \vec{r}(u, v)$ etc:

In Ex. 1 we used: $(u, v) = (r, \theta)$,

$$\vec{r}_r \times \vec{r}_\theta = \langle -2r\cos\theta, -2r\sin\theta, r \rangle$$

$$D \approx \left\{ \frac{1}{2} \leq r \leq \frac{3}{2}, 0 \leq \theta \leq 2\pi \right\}$$

3) Determine the \oplus or \ominus from the orientation of \vec{n} . ← NEW

- \vec{n} points inside the cone (given) \Rightarrow upwards (see picture)
 \Rightarrow z -component of \vec{n} is positive.

$$\bullet \vec{n} = \begin{array}{l} \oplus \\ \ominus \end{array} \frac{\vec{r}_r \times \vec{r}_\theta}{|\vec{r}_r \times \vec{r}_\theta|} = \begin{array}{l} \oplus \\ \ominus \end{array} \frac{\langle -2r\cos\theta, -2r\sin\theta, r \rangle}{\sqrt{5}r}$$

$$(\vec{n})_{z\text{-comp}} = \pm \frac{r}{\sqrt{5}r} > 0$$

$\begin{matrix} z\text{-component} \\ \text{of } \vec{n}; \\ \text{responsible for} \\ \text{"up" or "down".} \end{matrix}$

\Rightarrow must choose \oplus .

$$\text{So need } + (\vec{r}_r \times \vec{r}_\theta) = \langle -2r\cos\theta, -2r\sin\theta, r \rangle.$$

4) Substitute & evaluate:

$$\vec{F} \cdot (\vec{r}_r \times \vec{r}_\theta) = \left\langle -\underbrace{r \sin \theta}_{-y}, \underbrace{r \cos \theta}_x, \underbrace{3 \cdot (2r)^2}_{3z^2} \right\rangle \bullet$$

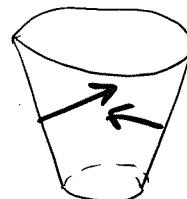
$$\langle -2r \cos \theta, -2r \sin \theta, r \rangle$$

$$= 2r^2 \sin \theta \cos \theta - 2r^2 \cos \theta \sin \theta + 12r^2 \cdot r = 12r^3.$$

$$\text{Flux} = \int_0^{2\pi} \left(\int_{1/2}^{3/2} 12r^3 \cdot dr \right) d\theta = 2\pi \cdot 15,$$

again, note that
this is not $r dr d\theta$.

Interpretation: Since \vec{n} points inside the cone, the above flux is the flow of \vec{F} into the cone. If \vec{F} represents the velocity of some fluid, then its flux measures how much fluid flows into the cone.



On the other hand, if \vec{n} points outside the cone, then the flux measures how much fluid flows out of the cone.

