

## Lecture 9      Euler's method

Goal: Solve  $\frac{dy}{dt} = f(t, y)$  approximately  
when it cannot be solved exactly.

① Idea: Approximate  $dy/dt$ :

$$\frac{dy}{dt} \approx \frac{y(t+h) - y(t)}{h} \quad \text{for small } h.$$

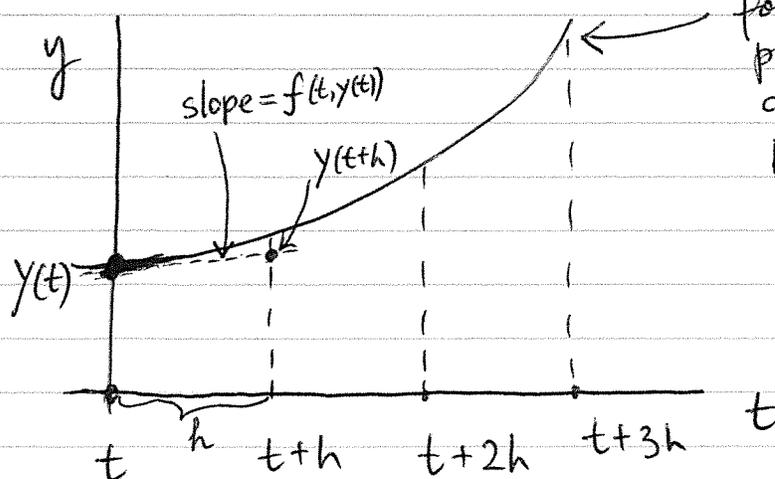
So, replace the DE with:

$$\frac{y(t+h) - y(t)}{h} = f(t, y(t))$$

and solve for the "new" value  $y(t+h)$   
using the known "old" value  $y(t)$ :

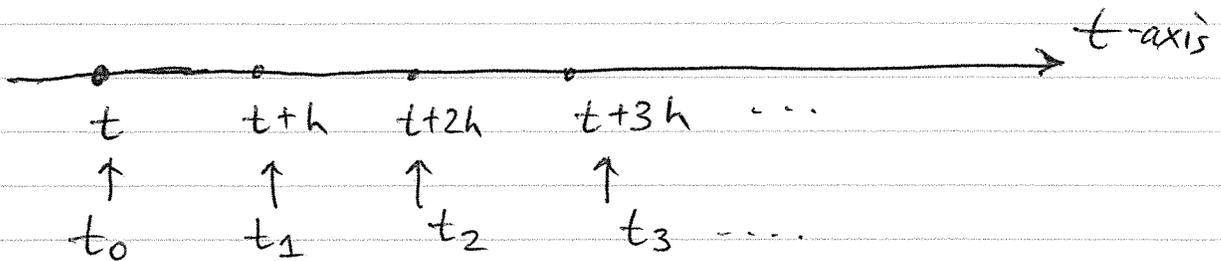
$$\boxed{y(t+h) = y(t) + h \cdot f(t, y(t))} \quad \text{Euler's Method.}$$

② Graphic representation



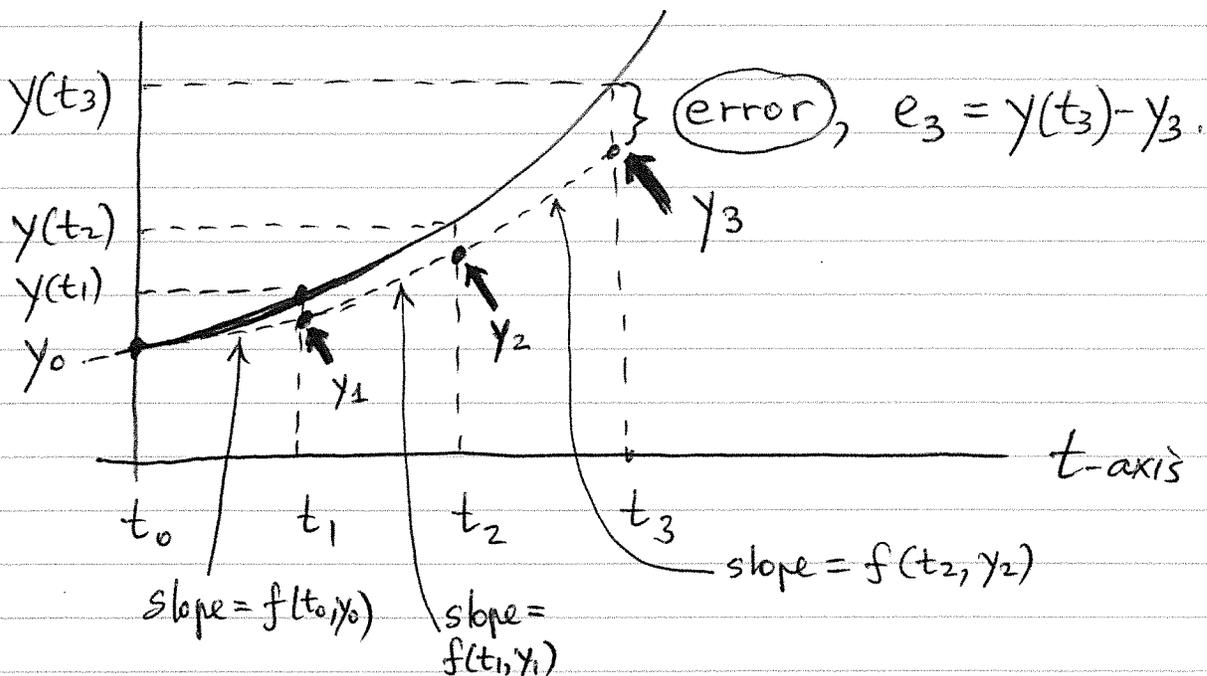
for this illustration  
purpose, let's  
assume that we  
know the sol'n  $y(t)$

Let's introduce a more convenient notation:



$$t_k = t_0 + k \cdot h, \quad k=0, 1, 2, \dots$$

Then we can redraw the previous figure:



Another notation: write Euler's method as

$$y_{k+1} = y_k + h \cdot f(t_k, y_k)$$

$y_k$  = approximate solution at  $t=t_k$ .  
 $y(t_k)$  = exact (and usually unknown) solution at  $t=t_k$

Ex. 1 Compute  $y_1, y_2, y_3$  for

$$y' = 0.5y + t, \quad y(t_0) = 3; \quad t_0 = 0;$$

while using  $h = 0.1$ .

Sol'n:

$$y_{k+1} = y_k + h \cdot f(t_k, y_k)$$

$= 3 \Rightarrow k = 2$  ← stop at  $k = 2$  (for  $y_3$ )

Decide of the  $k$  where you need to stop.

Thus need to do the calculations for  $k = 0, 1, 2$ .

$k = 0$

$$y_{\underbrace{0+1}_1} = y_0 + h \cdot f(t_0, y_0)$$
$$= 3 + 0.1 \cdot (0.5 \cdot y_0 + t_0)$$
$$= 3 + 0.1 \cdot (0.5 \cdot 3 + 0) = 3.15$$

$\downarrow y_1$

$k = 1$

$$y_{\underbrace{1+1}_2} = y_1 + h \cdot f(t_1, y_1)$$
$$= 3.15 + 0.1 \cdot (0.5 \cdot y_1 + t_1)$$
$$= 3.15 + 0.1 \cdot 1.675 = 3.3175$$

$\downarrow y_2$

$k = 2$

$$y_{\underbrace{2+1}_3} = y_2 + h \cdot f(t_2, y_2)$$
$$= 3.3175 + 0.1 \cdot (0.5 \cdot y_2 + t_2)$$
$$= 3.3175 + 0.1 \cdot 1.85875 = 3.503375$$

$\downarrow y_3$

Exact sol'n (Lec. 2):  $y(t_3) = 3.53284$

$\uparrow$  0.3

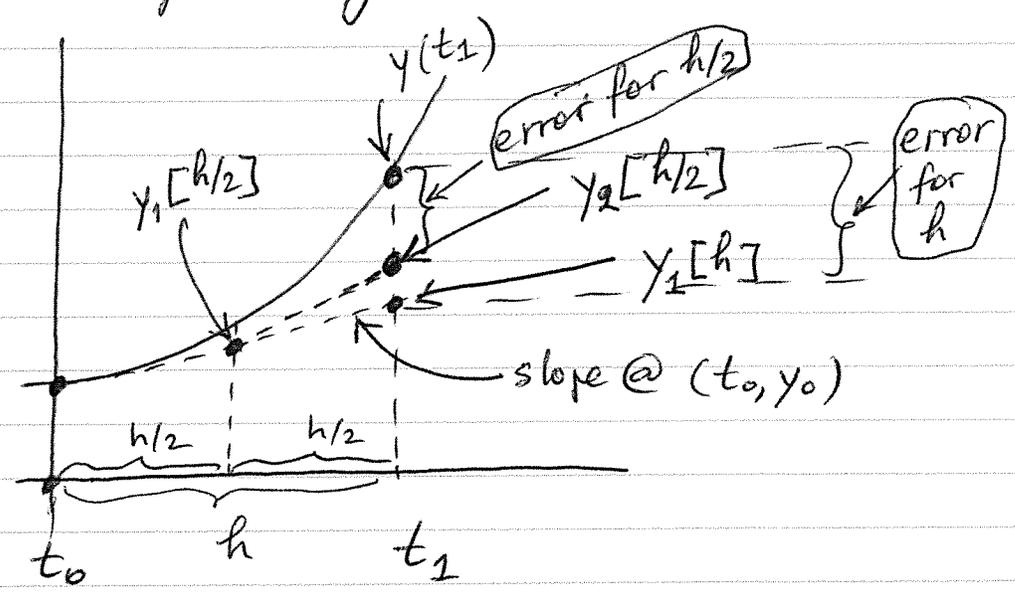
The error at  $t_3 = 0.3$  is

$$|y(t_3) - y_3| = |3.53284 - 3.503375| \approx 0.0295,$$

or  $\approx 0.9\%$ .

Note: The error will decrease if we take a smaller  $h$  (expectedly)!

Why? Graphically:

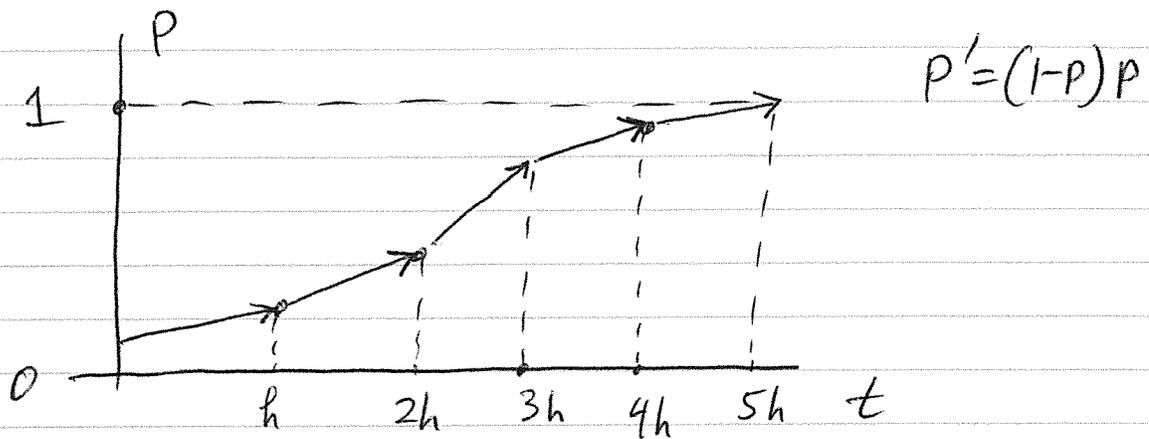


We see that  $y_2[h/2]$  is a better approximation to  $y(t_1)$  than  $y_1[h]$ .

Mnemonicly: The more accurate solution  $y_{2k}[h/2]$  is always found between the exact sol'n  $y'(t_k)$  and the less accurate sol'n  $y_k[h]$ .

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③ Relation to direction field:



The approximate solution found by Euler's method follows arrows of the direction field.

HW: Sec. 2.10 ## 3, 5.

Note: 1) Do not compute  $y_3$  &  $e_3$ .  
for both

2) In addition to the assigned calculation, repeat it for  $h=0.05$  and compute  $y_1, y_2, y_3, y_4$  for this new  $h$ , as well as  $e_1, e_2, e_3, e_4$ .

Verify that  $e_4 [h=0.05] \approx \frac{1}{2} e_2 [h=0.1]$ .

(In general,  $e_k = y(t_k) - y_k$  for a given  $h$ .)